
MODEL TI-25MXT

ULTRASONIC THICKNESS GAUGE



Operating Manual

TABLE OF CONTENTS

1.0 Introduction	3
1.1 Disclaimer	
2.0 Keypad, Menu, Display & Connectors	4
2.1 ON/OFF/ENTER Key	
2.2 PRB 0 Key	
2.3 CAL Key	
2.4 GAIN Key	
2.5 SCAN Key	
2.6 +/- INCREMENT/DECREMENT Keys	
2.7 MULTI Key....	
2.8 MENU Key...	
2.9 The Display	
2.10 The Transducer	
2.11 Top End Cap	
3.0 Principals of Ultrasonic Measurement	10
3.1 Time versus thickness relationship	
3.2 Suitability of materials	
3.3 Range of measurement and accuracy	
3.4 Couplant	
3.5 Temperature	
3.6 Measurement modes	
4.0 Selecting the measurement mode	13
4.1 Which Mode and Transducer do I use for my applications?	
5.0 Making measurements	15
5.1 Probe Zero	
5.2 Material calibration	
6.0 Through Paint Measurement – Multimode	21
6.1 Introduction	
6.2 Multimode transducers	
7.0 Velocity gauge	22
7.1 Velocity gauge (VX)	
7.2 Calibration to a known thickness	
7.3 Calibration to a known velocity	
8.0 Additional features	25
8.1 GAIN	
8.2 High-speed Scan	
8.3 Alarm	
8.4 Differential	
8.5 Units	
8.6 Lite	
8.7 Beep	

8.8	Zero	
8.9	Velocity (VX)	
8.10	Probe Diameter & Frequency	
8.11	Lock	
8.12	Factory Defaults	
9.0	Connectivity & Power	33
9.1	Connectivity	
9.2	Installing Serial Driver (CDC)	
9.3	Line power	
10.0	Appendix A - Velocity Table	36
11.0	Appendix B- Application Notes	38
12.0	Warranty	40

1.0 INTRODUCTION

The Checkline model TI-25MXT is a basic dual element thickness gauge with the ability to locate blind surface pitting and internal defects/flaws in materials. Based on the same operating principles as SONAR, the TI-25MXT is capable of measuring the thickness of various materials with accuracy as high as ± 0.001 inches, or ± 0.01 millimeters. The principle advantage of ultrasonic measurement over traditional methods is that ultrasonic measurements can be performed with access to only one side of the material being measured.

1.1 Disclaimer

Inherent in ultrasonic thickness measurement is the possibility that the instrument will use the second rather than the first echo from the back surface of the material being measured. This may result in a thickness reading that is TWICE what it should be. Responsibility for proper use of the instrument and recognition of this phenomenon rest solely with the user of the instrument. Other errors may occur from measuring coated materials where the coating is insufficiently bonded to the material surface. Irregular and inaccurate readings may result. Again, the user is responsible for proper use and interpretation of the measurements acquired.

2.0 KEYPAD, MENU, DISPLAY & CONNECTORS

The Keypad



2.1 ON/OFF/ENTER Key



The ON/OFF/ENTER key powers the unit ON or OFF. Since the same key is also used as an ENTER key, the gauge is powered off by pressing and holding down the key until the unit powers off.

Once the gauge is initially powered on, this key will function as the ENTER key, similar to a computer keyboard. This key will be used to select or set a menu option.

NOTE: Unit will automatically power off when idle for 5 minutes. All current settings are automatically saved prior to powering off.

2.2 PRB 0 Key



The PRB 0 key is used to “zero” the TI-25MXT in much the same way that a mechanical micrometer is zeroed. If the gauge is not zeroed correctly, all of the measurements that the gauge makes may be in error by some fixed value. Refer to section 5.1 for a further explanation of this important feature.

2.3 CAL Key



The CAL key is used to enter and exit the TI-25MXT’s calibration mode. This mode is used to adjust the sound velocity value that the TI-25MXT will use when calculating thickness. The tool will either calculate the sound-velocity from a sample of the material being measured, or allow a known velocity value to be entered directly. This provides increased linearity between transducers. Refer to section 5.2 for an explanation on the various calibration options.

2.4 GAIN Key



The TI-25MXT has an adjustable gain feature for additional versatility to control the overall output of the gauge, to compensate for various materials and applications. There are five gain settings (VLOW, LOW, MED, HIGH, VHI). The gain range is 40dB – 52dB in 3dB increments. Refer to section 8.1 for details regarding the GAIN feature.

2.5 SCAN Key

The TI-25MXT offers a high speed scan feature. This feature allows for scanning larger areas on a given test material, while still offering reasonable representation of thickness over the area scanned. Refer to section 8.2 for an explanation on the scan feature.

2.6 +/- Increment/Decrement Key's



The +/- keys are used to increment/decrement values, navigate menus, and select menu options.

2.7 MULTI Key



The MULTI key toggles between pulse-echo (P-E) and echo-echo (E-E) measurement modes. (P-E) is used primarily for flaw and pit detection, while (E-E) is used for through paint and coatings measurement without having to remove the paint/coating and eliminating any error as a result of the paint/coating. Refer section 6.0 for an explanation on Through Paint Measurement – Multimode.

2.8 MENU Key



The MENU key is used to access and set all of the additional features of the TI-25MXT that are not at the top level of the keypad with a dedicated key. The features and setting are outlined below:

Matl	Alarm	Dif	Unit	Lite	Beep	Zero	VX	Probe
Aluminum	On	On	English	On	On	Manual	On	.18 5
Steel	Off	Off	Metric	Off	Off	Auto	Off	.25 5
Stainless	Options	Options		Options				.25 7
Iron	Set Lo	Set Nominal		Lo				.50 3
Plexiglass	Set Hi			Med				.50 5
PVC				High				
Plastic								
Poly Urea								
User 1								
User 2								

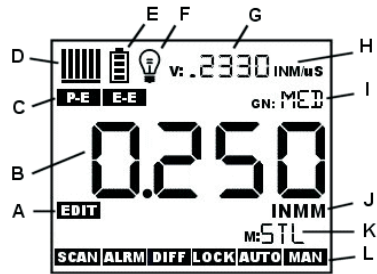
Here's a quick overview of navigating through the various features in MENU:

1. Press the **MENU** key once to enter the sub menu items
2. Press the **+** and **-** keys to toggle through the features.
3. To enable or edit the status of any feature, press the **ON/OFF/ENTER** key.
4. The edit icon will start blinking to indicate that the TI-25MXT is currently in **EDIT** mode.
5. Press the **+** and **-** keys to toggle through the setting options.
6. Press the **ENTER** key to accept changes and return to the top level of features, or the **MENU** key at any time to abort changes and return the measurement screen.

2.9 The Display

The TI-25MXT uses a custom glass LCD backlit low temperature display for use in a variety of climate conditions. It contains graphic icons, as well as both 7 and 14 segment display areas. Let's take a closer look and what all these things are telling us:

NOTE: This display is used for multiple gauge models in the TI series. As a result, some of the icons and segments that are illuminated during boot up, may not be applicable to your specific model, and will never be illuminated during operation. The icons and segments that will be used with the TI-25MXT are shown in the diagram above.



- A. Edit:** This icon will be displayed, and blinking, to let a user know when they are in an edit mode to change a value or setting.
- B. Large 7 segment:** The thickness measurement, velocity or alpha message will be displayed in this area.
- C. Measurement Modes:** This group of icons indicates which measurement mode the TI-25MXT is currently using. The modes are pulse-echo, for flaw and pit detection, and echo-echo for through paint and coating measurements.
- D. Stability/Repeatability Indicator:** This is used in conjunction with the thickness measurement as a reference for the validity of the measurement. The TI-25MXT takes multiple measurements per second, and when all the vertical bars are illuminated, it's a reference that the same thickness value is reliably being measured multiple times per second.
- E. Battery:** Indicates the amount of battery life the TI-25MXT has remaining.
- F. Backlight :** When this icon is illuminated, it indicates the backlight is on.

-
-
- G. Small 7 Segment:** The material velocity, speed the sound wave travels through a given medium/material, is displayed in this area, informing the user what material the TI-25MXT is currently calibrated too. This area is also used for alpha messages in the menu and edit modes.
 - H. Units:** This combination of icons are illuminated in different sequences to inform the user what measurement units are currently being displayed in the small 7 segment area.
 - I. Small 14 Segment:** Displays the current gain setting of the TI-25MXT. MED is the default, with the options of VLOW, LOW, MED, HIGH, VHI (40dB to 52db gain range with MED at 46dB).
 - J. Units:** This combination of icons are illuminated in different sequences to inform the user what measurement units are currently being displayed in the large 7 segment area.
 - K. Small 14 Segment:** The material type is displayed in this area. If it is set to a value of one of the materials in our material list, it will be displayed in alpha characters indicating the material type. Otherwise it will be set to CUST, indicating custom material type.
 - L. Features:** The icons illuminated in this row across the bottom of the LCD display which features are currently enabled. For a complete list of the menu features in the TI-25MXT , Refer to section 2.0 for a list. The TI-25MXT can be locked once calibrated, to avoid accidentally changing the calibration. When this icon is illuminated, the TI-25MXT is in lock mode. Refer section 6.7 for an explanation on locking the TI-25MXT .

2.10 The Transducer



The transducer is the “business end” of the TI-25MXT . It transmits and receives ultrasonic sound waves that the TI-25MXT uses to calculate the thickness of the material being measured. The transducer connects to the TI-25MXT via the attached cable, and two coaxial connectors. When using transducers manufactured by Checkline, the orientation of the dual coaxial connectors is not critical: either plug may be fitted to either socket in the TI-25MXT.

The transducer must be used correctly in order for the TI-25MXT to produce accurate, reliable measurements. Below is a short description of the transducer, followed by instructions for its use.

This is a bottom view of a typical transducer. The two semicircles of the wear face are visible, as is the barrier separating them. One of the semicircles is responsible for conducting ultrasonic sound into the material being measured, and the other semicircle is responsible for conducting the echoed sound back into the transducer. When the



transducer is placed against the material being measured, it is the area directly beneath the center of the wear face that is being measured.

This is a top view of a typical transducer. Press against the top with the thumb or index finger to hold the transducer in place. Moderate pressure is sufficient, as it is only necessary to keep the transducer stationary, and the wear face seated flat against the surface of the material being measured.



Measuring

In order for the transducer to do its job, there must be no air gaps between the wear-face and the surface of the material being measured. This is accomplished with the use of a “coupling” fluid, commonly called “couplant”. This fluid serves to “couple”, or transfer, the ultrasonic sound waves from the transducer, into the material, and back again. Before attempting to make a measurement, a small amount of couplant should be applied to the surface of the material being measured. Typically, a single droplet of couplant is sufficient.

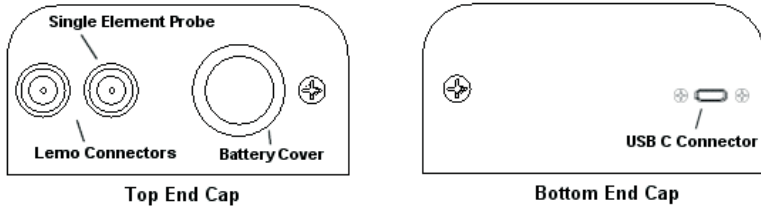
After applying couplant, press the transducer (wear face down) firmly against the area to be measured. The Stability Indicator should have six or seven bars darkened, and a number should appear in the display. If the TI-25MXT has been properly “zeroed” (see page 15) and set to the correct sound velocity (see page 16), the number in the display will indicate the actual thickness of the material directly beneath the transducer.

If the Stability Indicator has fewer than five bars darkened, or the numbers on the display seem erratic, first check to make sure that there is an adequate film of couplant beneath the transducer, and that the transducer is seated flat against the material. If the condition persists, it may be necessary to select a different transducer (size or frequency) for the material being measured. See page 7 for information on transducer selection.

While the transducer is in contact with the material that is being measured, the TI-25MXT will perform four measurements every second, updating its display as it

does so. When the transducer is removed from the surface, the display will hold the last measurement made.

2.11 Top End Cap



The top end cap is where all connections are made to the TI-25MXT . The diagram above shows the layout and description of the connectors.

Transducer Connectors

Refer to Diagram: The transducer connectors and battery cover/probe zero disk are located on the TI-25MXT 's top end cap. The transducer connectors are of type Lemo “00”.

NOTE: There is no polarity associated with connecting the transducer to the TI-25MXT, it can be plugged into the gauge in either direction.

Probe Zero Disk & Battery Cover

Refer to Diagram: The Battery cover is the large round disk shown in the diagram.

NOTE: This same disk is also used as a probe zero reference disk. Simply remove the cover when replacing the batteries (2 AA cells). When performing a manual probe zero function, simply place the transducer on disk making firm contact. **Important:** Be sure the battery polarity is correct, which can be found on the back label of the TI-25MXT .

NOTE: Rechargeable batteries can be used, however they must be recharged outside of the unit in a standalone battery charger.

USB-C Connector

Refer to Diagram: The USB-C connector, located on the bottom end cap, is a mini type C female connector. It is designed to connect directly from the TI-25MXT to a standard USB type A port on a PC. The cable supplied with the TI-25MXT is a USB type C to a USB type A (p/n N-003-0330). See section 9.1 for information on connectivity.

NOTE: This connector is also used to upgrade the TI-25MXT with the latest version of firmware.

3.0 PRINCIPLES OF ULTRASONIC MEASUREMENT

3.1 Time versus thickness relationship

Ultrasonic thickness measurements depend on measuring the length of time it takes for sound to travel through the material being tested. The ratio of the thickness versus the time is known as the sound velocity. In order to make accurate measurements, a sound velocity must be determined and entered into the instrument.

The accuracy of a thickness measurement therefore depends on having a consistent sound velocity. Some materials are not as consistent as others and accuracy will be marginal. For example, some cast materials are very granular and porous and as a result have inconsistent sound velocities.

While there are many different ultrasonic techniques to measure thickness, which will be discussed below, all of them rely on using the sound velocity to convert from time to thickness.

3.2 Suitability of materials

Ultrasonic thickness measurements rely on passing a sound wave through the material being measured. Not all materials are good at transmitting sound. Ultrasonic thickness measurement is practical in a wide variety of materials including metals, plastics, and glass. Materials that are difficult include some cast materials, concrete, wood, fiberglass, and some rubber.

3.3 Range of measurement and accuracy

The overall measurement capabilities, based on the wide variety of materials, is determined by the consistency of the material being measured

The range of thickness that can be measured ultrasonically depends on the material type and surface, as well as the technique being used and the type of transducer. The range will vary depending on the type of material being measured.

Accuracy, is determined by how consistent the sound velocity is through the sound path being measured, and is a function of the overall thickness of the material. For example, the velocity in steel is typically within 0.5% while the velocity in cast iron can vary by 4%.

3.4 Couplant

All ultrasonic applications require some medium to couple the sound from the transducer to the test piece. Typically a high viscosity liquid is used as the medium. The sound frequencies used in ultrasonic thickness measurement do not travel through air efficiently. By using a liquid couplant between the transducer and test piece the amount of ultrasound entering the test piece is much greater.

3.5 Temperature

Temperature has an effect on sound velocity. The higher the temperature, the slower sound travels in a material. High temperatures can also damage transducers and present a problem for various liquid couplants.

Since the sound velocity varies with temperature it is important to calibrate at the same temperature as the material being measured.

Normal temperature range

Most standard transducers will operate from 0°F to 250°F.

High temperature measurements

Special transducers and couplants are available for temperatures above 250°F up to 1000°F with intermittent contact. It is necessary to cool the transducer by submerging it in water between measurements.

Modes and temperature errors

In addition to errors caused by velocity changing with temperature, some modes (measurement techniques) are affected more than others. For example, dual element pulse-echo mode has larger errors due to changes in the temperature of the transducer. However, multi-echo techniques offer temperature compensation help to minimize these errors.

3.6 Measurement Modes

This section will cover the different measurements modes of the TI-25MXT, the transducers required, and the reasons for using specific modes:

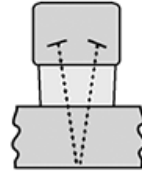
Pulse-Echo (P-E) Mode:

Pulse-echo mode measures from the initial pulse (sometimes referred to as an artificial zero) to the first echo (reflection). In this mode, either an automatic or manual zero can be performed depending on the zero probe setting. If the manual mode has been selected, the transducer is placed on the reference disk located on top of the TI-25MXT, and the PRB 0 key pressed to establish a zero point for the transducer connected. If the Auto Zero feature is enabled, simply pressing the PRB 0 key will perform an electronic zero to establish the same zero point.

In pulse-echo mode, errors can result from surface coatings and temperature variations. Since pulse-echo only requires one reflection, it is the most sensitive mode for measuring flaw/defects when measuring heavily corroded metals.

V-Path Correction

Dual element delay line transducers have two piezoelectric elements focused towards one another at a slight angle, mounted on a delay line. One element is used for transmitting sound, while the other element receives the sound reflection. The two elements and their delay lines are packaged in a single housing but acoustically isolated from each other with an insulated sound barrier. This allows the transducer the ability to achieve very high sensitivity for detecting small defects. Also, the surface of the test material does not have to be as flat in order to obtain good measurements.



Dual Element Transducer showing V-path of signal

Dual element transducers are normally used in pulse-echo mode for finding defects, and in echo-echo mode for through coating measurements.

Dual element delay line transducers have a usable range of 0.025" and up, depending on the material, frequency, and diameter.

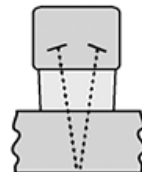
A limitation of dual element delay-line transducers is the V shaped sound path. Because the sound travels from one element to another, the time versus thickness relationship is non-linear. Therefore, a correction table in the instruments software is used to compensate for this error.

Searching for small defects

Dual element delay line transducers are especially useful in searching for small defects. In pulse-echo mode with high amplifier gain, very small defects can be located. As a result, this configuration is commonly used for corrosion inspections. The dual element style transducer will find wall deterioration, pits, cracks, and any porosity pockets during tank and pipeline inspections.

Echo-Echo (E-E) Mode – Through Paint

The echo-echo mode measures between the first and second return echoes/reflections. This technique is commonly used when measuring through a surface coating and measuring only the second layer of material. Tanks and pipes commonly have a protective coating applied to the surface. Echo-echo mode will enable the user to measure just the steel without having to remove the coating. The disadvantage is that



Dual Element Transducer in Echo-Echo mode

two return echoes are required to effectively measure the test material. Additionally, echo-echo mode does not have the capability to find defects. Therefore, both modes will commonly be used; echo-echo mode to find the nominal thickness of the material without removing the coating, and pulse-echo to locate defects.

4.0 SELECTING THE MEASUREMENT MODE

4.1 Which mode & transducer do I use for my application?

High penetration plastics and castings

The most common mode for these types of applications is pulse-echo. Cast iron applications require 1 - 5MHz frequencies, and cast aluminum requires a 7 - 10MHz frequency depending on the thickness. Plastics typically require lower frequencies depending on the thickness and make-up of the material as well. Larger diameters offer greater penetration power based on the size of the crystal.

Corrosion & Pit Detection in steel and cast materials

Pulse-echo mode is commonly used for locating pits and defects. Typically a 5MHz transducer, or higher, will be used for these types of applications. Use low frequencies for greater penetration and use higher frequencies for better resolution.

Measuring Material & Coatings

The pulse-echo coating mode should be used when both material and coating thickness are required, while still requiring the ability to detect flaws and pits. A special coating style transducer is required for use in this mode. There are a variety of coating transducers in various frequencies available from Electromatic.

Thru Paint & Coatings

Often times, users will be faced with applications where the material will be coated with paint or some other type of epoxy material. Since the velocity of the coating is approximately 3 times slower than that of steel, pulse-echo mode will result in an error if the coating or paint is not completely removed.

Thin materials

Pulse echo mode and a high frequency transducer is commonly used for these types of applications. The most common transducers are the 7.5MHz and 10MHz models with extra resolution. The higher frequencies provide greater resolution and a lower minimum thickness rating overall.

High temperature

Special 5 MHz High temperature transducers are available for these types of applications. Both pulse-echo and echo-echo modes will also work for these applications. However, echo-echo mode will eliminate error caused by temperature variations in the transducer.

Noisy Material

Materials such as titanium, stainless steel, and aluminum may have inherent surface noise issues or mirroring effect. Higher frequency transducers 7 – 10MHz offer improved resolution to avoid erroneous measurements.

Restricted access

Measuring materials with extreme curvatures or restricted access are best suited for higher frequencies and smaller diameter transducers.

5.0 MAKING MEASUREMENTS

The steps involved in making measurements are detailed in this section. The following sections outline how to setup and prepare your TI-25MXT for field use.

An automatic or manual zero must always be performed. The auto zero is an ‘off block’ electronic zero that does not require a zero reference standard. This will most always be the zero option of choice, as it makes the zeroing process very easy and convenient to perform. However, the manual zero option offers better accuracy in terms of a reference point. If the manual zero option is enabled, the probe zero must be measured on the reference disk (battery disk) attached to the top of the instrument. The zero compensates for variations in the transducer. In either mode the sound velocity must be determined, and is used to convert the transit time to a physical length. The sound velocity can be selected from a material chart in the manual, selected from a short list of common materials in the TI-25MXT, or for greater precision determined from a sample of the test material that has been mechanically measured. To enter the velocity from a table, look up the material on the chart in the appendix of this manual and refer to the section below on Calibration to a Known Velocity. To determine the velocity of a single sample, refer to the Material Calibration section in section 5.2.

When measuring curved materials, it’s more accurate to calibrate from two test points, one at the minimum limit of the target thickness and one at the maximum limit. In this case the reference disk mounted to the TI-25MXT is not used. This is called two-point calibration and is described in section 5.2

5.1 Probe zero

Setting the zero point of the TI-25MXT is important for the same reason that setting the zero on a mechanical micrometer is important. It must be done prior to calibration, and should be done throughout the day to account for any temperature changes in the probe. If the TI-25MXT is not zeroed correctly, all the measurements taken may be in error by some fixed value. The zero can only be performed with the measurement mode set to pulse-echo (P-E). Therefore, if the TI-25MXT is to use the echo-echo (E-E) measurement mode and a manual zero is being performed, the TI-25MXT will argue by briefly displaying the message “NO PRB0”.


IMPORTANT NOTE: The internal zero setting of the TI-25MXT, used for the auto zero mode, can be reset at anytime by performing a “manual zero”, and immediately followed by performing an “auto zero”.

The TI-25MXT is equipped with two zero options:

1. **Off Block Zero (Automatic Probe Zero)** – When this feature is enabled the TI-25MXT will do an electronic zero automatically, eliminating the need for a zero disk or reference standard.
2. **On Block Zero (Manual Probe Zero)** – When this feature is enabled the transducer must be placed on the probe zero disk (battery cover) located on the top of the unit.


Both zero procedures are outlined as follows:

Performing an Auto Probe Zero (Off Block)

1. Be sure all couplant has been removed from the face of the transducer.
2. Press the  key to perform the auto zero. “AUTO ZERO” will briefly be displayed on the screen, indicating the zero calculation is being performed.

Performing a Manual Probe Zero (On Block)

NOTE: When the zero probe option is set to manual, the probe zero disk (battery cap) located on the top of the gauge will be used as a zero standard.

1. Apply a drop of couplant on the transducer and place the transducer in steady contact with the disk (battery cover) located at the top of the unit to obtain a measurement.
2. Be sure all six repeatability/stability bars in the top left corner of the display are fully illuminated and stable, and last digit of the measurement is toggling only +/- .001” (.01mm).
3. Press the  key to perform the manual zero. “PRB0” will briefly be displayed on the screen, indicating the zero calculation is being performed.




5.2 Material Calibration

In order for the TI-25MXT to make accurate measurements, it must be set to the correct sound velocity of the material being measured. Different types of materials have different inherent sound velocities. For example, the velocity of sound through steel is about 0.233 inches per microsecond, versus that of aluminum, which is about 0.248 inches per microsecond. If the gauge is not set to the correct sound velocity, all of the measurements the gauge makes will be erroneous by some amount.



The One Point calibration is the simplest and most commonly used calibration method—optimizing linearity over large ranges. The Two Point calibration allows for greater accuracy over small ranges by calculating both the probe zero, as well as the material velocity. The TI-25MXT provides three simple methods for setting the sound-velocity outlined on the following page:


Known Velocity

If the material velocity is known, it can be manually entered into the TI-25MXT, rather than have the TI-25MXT calculate the velocity value using a known thickness of the same material type. The steps for entering the velocity are outlined below:

1. With the transducer free from contact with the material, press the  key to display the current velocity.
2. Use the  and  keys to scroll the velocity to the known target value.

NOTE: The longer the keys are pressed and held, the faster the value will increment/decrement.

NOTE: Pressing the  key prior to pressing the  key will abort the calibration routine without saving any changes.

3. Press the  key to set the velocity value and return to the measurement screen. The new velocity value will be shown at the top of the display.

Known Thickness


Often times the exact sound velocity of a material is unknown. However, a sample with one or two known thicknesses can be used to determine the sound velocity. As previously discussed, the TI-25MXT has a one or two point calibration option. The one point calibration option is most suited for linearity over large ranges. When using the one point option, the calibration should be performed on the thickest side of the measurement range for the best linearity for that range. For example, if the measurement range is .100" (2.54mm) to 1.0" (25.4mm), the user should calibrate on a known thickness sample close to 1.0" (25.4mm). Note: It's always handy to carry a set of mechanical calipers to use in conjunction with the TI-25MXT for calibration of various materials in the field:


One Point Calibration

NOTE: Be sure that a probe zero has been performed prior to performing this calibration procedure.



1. Physically measure an exact sample of the material, or a location directly on the material to be measured, using a set of calipers or a digital micrometer.

NOTE: A sample or location on the test piece should be used as close to the maximum thickness of the test range to minimize error.



2. Apply a drop of couplant on the transducer and place the transducer in steady contact with the sample or actual test material. Be sure that the reading is stable and the repeatability indicator in the top left corner of the display is fully lit and stable.
3. Press the  key to enter the calibration edit screen displaying the current measurement value.


-
-
4. Use the  and  keys to scroll to the known thickness value.

NOTE: The longer the keys are pressed and held, the faster the value will increment/decrement.

NOTE: Pressing the  key prior to pressing the  key will abort the CAL routine without saving any changes.

5. Once the known thickness value is being displayed, press the key to display the calculated material velocity edit screen.

NOTE: The calculated velocity can be edited, if needed, by pressing the  and  keys to scroll and edit the velocity value.

6. Press the  key to set the calculated material velocity and return to the measurement screen.

CHECK YOUR CALIBRATION! Place the transducer back on the calibration point and verify the thickness. If the thickness is not correct, repeat the steps above.

Two Known Thicknesses

The two point calibration should be considered when an application requires improved accuracy over a small measurement range based on tolerance requirements. This calibration option calculates both the 'probe zero' and 'velocity value'. If the two point option is used, a probe zero is not required. For example, if the measurement range was .080" (2.03mm) to .250" (6.35mm), two known samples or locations on the test material would be needed for the minimum and maximum boundaries of the test range. Using the range above, a one point calibration would be performed at .250" (6.35mm) and a two point calibration at .080" (2.03mm), or something close to the min/max values of the measurement range.

NOTE: The TI-25MXT also offers the capability of setting the 'probe zero' to use any reference standard as the 'probe zero' standard. For clarification, if it's desired to use a one inch reference of a specific material type as the 'zero' reference, performing the first point of a two-point calibration sets the internal zero of the TI-25MXT. This should be used only in manual probe zero mode "on block".


The following steps outline this procedure:

Two Point Calibration

1. Physically measure a minimum and maximum calibration point of the exact sample material, or locations directly on the material to be measured, using a set of calipers or a digital micrometer.



NOTE: A sample or location on the test piece should be used as close to the minimum and maximum thickness of the test range to minimize error and improve linearity.


2. Apply a drop of couplant on the transducer and place the transducer in steady contact with either the minimum or maximum sample or actual test material. Be sure that the reading is stable and the repeatability indicator in the top left corner of the display is fully lit and stable.

3. Press the  key to enter the calibration edit screen displaying the current measurement value.

4). Use the  and  keys to scroll to the known thickness value.

NOTE: The longer the keys are pressed and held, the faster the value will increment/decrement.

NOTE: Pressing the  key prior to pressing the  key will abort the cal routine without saving any changes.


5. Once the known thickness value is being displayed, press the  key to display “1 of 2”, which sets the zero value and returns to the measurement screen.

NOTE: The internal zero of the TI-25MXT is now set. The procedure above can be used to set the internal zero of the TI-25MXT to use any reference standard as the ‘probe zero’ standard if desired.

6. Repeat steps 2–4 on the second test point/location.

7. Press the  key to display the calculated velocity edit screen.

NOTE: The calculated velocity can be edited, if needed, by pressing the keys to scroll and edit the velocity value.




8. Press the  key to set the calculated material velocity and return to the measurement screen.

NOTE: CHECK YOUR CALIBRATION! Place the transducer back on the calibration points. The thickness readings should now match the known thickness values with minimal error. If the thicknesses are not correct, repeat the steps above.


Basic Material Type



If the material velocity is unknown, a sample thickness cannot be taken directly from the material, but the general type of material is known, selecting a basic material type from the common material (MATL) list in the TI-25MXT would offer a reasonable approximation of the thickness. There are 9 common materials and 2 user programmable settings available. It’s important to note that these velocities will not always be an exact representation of the material being tested. Use these values only if a close approximation is acceptable. Follow the steps below to select a basic material type:

Selecting a Basic Material Type

1. Press the  key to access the material list. The edit icon will be illuminated and flashing.
2. Use the  and  keys to scroll through the material options.

		in/μs	m/s
ALU	ALUMINUM (2024)	0.250	6350
STL	STEEL (4340)	0.233	5918
STS	STAINLESS (303)	0.223	5664
Iron	CAST IRON	0.180	4572
PLX	PLEXIGLASS	0.106	2692
PVC	PVC	0.094	2388
PLS	POLYSTYRENE	0.092	2337
PLU	POLYURETHANE	0.070	1778
USR1	} USER PROGRAMMABLE		
USR2			


3. When the desired MATL setting is displayed, press the  key to set the material velocity and return to the measurement screen.



NOTE: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving any changes.

4. If USR1 or USR2 were selected, the velocity edit screen will be displayed and edit icon illuminated and flashing.

5. Use the  and  keys to scroll to the desired material velocity.

NOTE: The longer these keys are held, the faster the velocity value is incremented.

6. When the desired velocity setting is displayed, press the  key to set the material velocity and return to the measurement screen.

NOTE: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.

6.0 THROUGH PAINT MEASUREMENT – MULTIMODE

6.1 Introduction

Through paint measurement is accomplished by measuring the time between two repeat echoes from the back surface of the material. Since both of these back wall echoes travel the same path through the paint or coating, the thickness of the coating is subtracted out of the measurement so that only the actual material thickness is measured. This avoids having to scrape or remove the coating from materials prior to inspection. The primary purpose of thru paint measurement is to determine the actual/nominal material thickness without error from the coating.

Through paint mode cannot be used for flaw or pit detection based on the internal gating and thresholds. As a result, inspectors will typically use both echo-echo through paint mode in conjunction with the standard pulse-echo flaw detection mode for coated material and corrosion inspection. Finally, this mode will only work for typical epoxy based coatings.


6.2 Multi Mode Transducers

The multi echo measurement technique does have restrictions on the type of dual element transducers it can use successfully. The key requirement is that the transducers are “highly damped”, which refers to the duration of how long the transducer rings. In order to improve the low end measurement range, ability to measure thin materials, the cycles of ring down must be limited so they don’t interfere with the internal gating.

Since the TI-25MXT is a basic easy to operate gauge without the adjustability you’d get using an advanced A-Scan scope, specific diameter and frequency options can be selected as an option in the menu items. The factory default setting is (.25 5) or 0.250” 5MHz, as the most commonly requested transducer. Refer to page 5 for a list of available high damped transducer diameters and frequencies.

The procedure for activating the through paint (E-E) measurement mode is outlined as follows:

NOTE: Be sure that a probe zero and “one point calibration”, or a “two point calibration” has been performed prior to this procedure.

1. Press the  key to toggle between the measurement modes; pulse-echo (P-E) and echo-echo (E-E) at any time.

NOTE: An icon will be illuminated in the top left portion of the display to indicate the measurement mode the TI-25MXT is currently using.







7.0 VELOCITY GAUGE



7.1 Velocity Gauge (VX)

The TI-25MXT includes a function to convert the unit into a dedicated velocity gauge. With this feature enabled, the TI-25MXT will display all measurements in terms of velocity, inches per microsecond (IN / μ s) or meters per second (M /s), rather than dimensional inches or millimeters. This is primarily useful for rudimentary “nodularity” testing, as the velocity can be associated with density and used to determine the hardness/strength of a given material. A casting manufacturer would typically use this feature to control their processes and make sure the density/hardness is sufficient for each part and batch within a specified tolerance.

Using this feature will require calibration on a “known” thickness that will remain consistent at a specific location on a group of parts. The test will always be performed at the same location for all parts in the group. The velocity will be determined, and either accepted or rejected depending on the specified tolerances.

The procedure for enabling this feature is outlined below:

1. Press the  key to access the menu items/features.
2. Use the  and  keys to scroll through the items/features until the VX feature is being displayed.
3. Press the  key to edit the velocity gauge setting. The edit icon will be illuminated and flashing.
4. Use the  and  keys to toggle velocity on/off.

NOTE: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.





5. When the desired VX setting is displayed, press the key to set the status and return to the measurement screen.

7.2 Calibration to a known thickness



In order to calibrate the TI-25MXT a ‘known thickness’ on the material or part will be used. The same location will be used for all the other parts in the group/batch to determine the velocity.


The procedure is outlined as follows:

NOTE: Be sure that a probe zero has been performed prior to performing this calibration procedure.

1. Physically measure an exact sample of the material, or a location directly on the material to be measured, using a set of calipers or a digital micrometer.
2. Apply a drop of couplant on the transducer and place the transducer in steady contact with the sample or actual test material. Be sure that the reading is stable and the repeatability indicator, in the top left corner of the display, is fully lit and stable.
3. Press the  key to enter the calibration edit screen displaying the current velocity IN / μ s (M /s) value. The edit icon will be illuminated and flashing.
4. Press the  key again to edit the known thickness value. The edit icon will be illuminated and flashing and the units will be IN or MM, indicating thickness.
5. Use the  and  keys to scroll to the known thickness value.

NOTE: The longer the keys are pressed and held, the faster the value will increment/decrement.

NOTE: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.

6. Once the known thickness value is being displayed, press the  key to return to the measurement screen and display the calculated material velocity.

NOTE: The known thickness value that was used to calibrate will be displayed in the top right corner of the display for confirmation.

7.3 Calibration to a known velocity

The velocity can also be directly edited and set to a target velocity value that was previously determined from a reference standard at an earlier time.




The procedure for directly entering the velocity is outlined below:



NOTE: Be sure that a probe zero has been performed prior to performing this calibration procedure.



NOTE: This procedure requires that the operator know the sound-velocity of the material to be measured. A table of common materials and their sound-velocities can be found in Appendix A.

1. Apply a drop of couplant on the transducer and place the transducer in steady contact with the sample or actual test material. Be sure that the velocity

measurement is stable and the repeatability indicator, in the top left corner of the display, is fully lit and stable.

2. Press the  key to enter the calibration edit screen displaying the current velocity IN / μ s (M /s) value. The edit icon will be illuminated and flashing.
3. Use the  and  keys to scroll to the known velocity value.

NOTE: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.

4. Once the known velocity value is being displayed, press the  key to display the calculated thickness based on known velocity.
5. Press the  key to return to the measurement screen and begin making measurements.

NOTE: The known velocity value that was entered will be displayed, and the thickness value calculated will appear in the top right corner of the display for confirmation.

8.0 ADDITIONAL FEATURES

8.1 Gain




The gain, or amplification of the return echoes, can be adjusted in the TI-25MXT to accommodate a variety of materials and applications. The setting of the gain is crucial in order to obtain valid readings during the measurement process. Too much gain may result in erroneous measurements, detecting on noise rather than the actual material back wall surface. Not enough gain may result in intermittent detection. It could also result in lack of detection on internal flaws, pits, or porosity. The gain can be compared to the volume control of a home stereo system. If you turn it up too much, you can't hear the music clearly. If it's turned down too much, you can't hear it at all.

The TI-25MXT has five gain settings (VLOW, LOW, MED, HIGH, VHI). The gain range is 40dB – 52dB in 3dB increments. The TI-25MXT has been optimized for the MED gain setting at 46dB for all common applications. It should be operated in this mode as standard. However, some applications may require the lower or higher gain settings. When? The low settings may be necessary for noisy or granular cast materials. How do I know when to lower the gain? If the reading becomes sporadic and won't settle down or resolve on a thickness value because the material is either very noisy or granular. Setting the gain to a lower less sensitive level, would potentially offer improved stability.



How do I know when to increase the gain? When a material is difficult to penetrate or pass sound through. This could be due to the material type, overall thickness, the transducer diameter and frequency, or a combination of all the above. Turning the gain up for additional output could improve the ability to obtain a successful measurement. Another example would be the need to increase overall sensitivity for locating fine pits or flaws. In any case, the selectable gain settings offer improved versatility to resolve and overcome potential application issues.

NOTE: When the echo-echo through paint measurement mode is selected, the automatic gain control (AGC) is enabled. The dynamic range of the AGC can be adjusted with the following options (LOW, MED, HIGH), with MED still being the optimized standard setting as above.

The procedure for editing the gain is outlined as follows:

1. Press the  key to access the menu items/features. The edit icon will be illuminated and flashing
2. Use the  and  keys to scroll to gain settings in P-E (VLOW, LOW, MED, HIGH, VHI) or E-E (LOW, MED, HIGH) until the desired setting is displayed.

-
-
-
3. Press the  key to edit the gain setting. The edit icon will be illuminated and flashing.


NOTE: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.

5. When the desired GAIN setting is displayed, press the  key to set the gain and return to the measurement screen.

8.2 High Speed Scan

The High Speed Scan feature of the TI-25MXT increases the overall repetition rate to a maximum of 140Hz with a high speed screen refresh rate of 25 times a second. This allows for making scanned passes over an arbitrary length of the test material, while still maintaining a reasonable representation of thickness over the area or region scanned.







The procedure to use the scan feature is outlined below:

1. Press the  key to toggle the SCAN on/off. the display will briefly show the status and return to the measurement screen..



8.3 Alarm



The Alarm feature of the TI-25MXT provides a method of setting tolerances, or limits, for a particular application requirement. This feature may be used for a variety of applications to verify the material thickness is within the manufacturer specifications. The settings available are ON/OFF/BEEP, where beep enables the audible beeper. Both the on and beep settings will illuminate the led alarm lights above the keys on the keypad. There are two limit values HI/LO, that can be set according to specified tolerances.


The procedure to use the alarm feature is outlined below:



1. Press the  key to access the menu items/features.
2. Use the  and  keys to scroll through the items/features until the ALRM feature is being displayed.
3. Press the  key to edit the alarm status. The edit icon will be illuminated and flashing.
4. Use the  and  keys to toggle alarm on/off/beep.



5. When the desired ALRM status is displayed, press the  key to set the status and edit the LO limit option.


6. Use the  and  keys to scroll the LO limit value to the target value.

Note: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes to the LO limit value.

7. When the target LO limit is displayed, press the  key to set the value and advance to setting HI limit option.

8. Use the  and  keys to scroll the HI limit value to the target value.


Note: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes to the LO limit value.

9. When the target HI limit is displayed, press the  key to set the value and return to the measurement screen.

8.4 Differential

The Differential Mode of the TI-25MXT provides the user with the ability to set a nominal value, according to what the expected thickness should be, and measure the +/- difference from the nominal value entered. This feature is typically used in QA incoming inspections on pipes, plate stock, coils, etc.

The steps below outline how to enable and enter the nominal value to use this feature:



1. Press the  key to access the menu items/features.



2. Use the  and  keys to scroll through the items/features until the DIFF feature is being displayed.


3. Press the key to edit the differential status. The edit icon will be illuminated and flashing.

4. Use the  and  keys to toggle differential on/off.

5. When the desired DIFF setting is displayed, press the  key to set the status and edit the NOMINAL value.

6. Use the  and  keys to scroll the NOMINAL value to the target value.







Note: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.



7. When the target value is displayed, press the  key to set the value and return to the measurement screen.


8.5 Units

The TI-25MXT will operate in both English (inches) or Metric (millimeters) units.

The procedure to select the units is outlined as below:

1. Press the  key to access the menu items/features.
2. Use the  and  keys to scroll through the items/features until the UNIT feature is being displayed.
3. Press the  key to edit the units setting. The edit icon will be illuminated and flashing.
4. Use the  and  keys to toggle English or Metric units.







Note: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.

5. When the desired UNIT setting is displayed, press the  key to set the units and return to the measurement screen.

8.6 Lite

The TI-25MXT uses a custom glass segmented display that is equipped with a backlight for use in low light conditions. The options are on/off/auto, where the auto setting only lights the display when the gauge is coupled to the material and receiving a measurement.

The steps below outline how to toggle the options:

1. Press the  key to access the menu items/features.
2. Use the  and  keys to scroll through the items/features until the LITE feature is being displayed.
3. Press the  key to edit the light setting. The edit icon will be illuminated and flashing.
4. Use the  and  keys to toggle status on/off/auto.

Note: Pressing the  key prior to pressing the



key will abort to the

5. When the desired LITE setting is displayed, press the



key to set the status and edit the BRT (brightness) option.

6. Use the



keys to scroll through the BRT (LO, MED, HI) options.

7. When the desired BRT setting is displayed, press the



key to set the brightness and return to the measurement screen.

Note: Pressing the  key prior to pressing the



key will abort to the measurement screen without saving changes.


8.7 Beep

The TI-25MXT also has a feature to use the internal beeper, most commonly used with the alarm feature, for the key strokes on the keypad. When enabled, pressing any of the keys on the keypad will sound the beeper.

The procedure to enable the keyboard beeper feature is outlined below:

1. Press the  key to access the menu items/features.

2. Use the  and  keys to scroll through the items/features until the BEEPER feature is being displayed.

3. Press the  key to edit the beeper setting. The edit icon will be illuminated and flashing.

4. Use the  and  keys to toggle the beeper on/off.

Note: Pressing the  key prior to pressing the



key will abort to the measurement screen without saving changes.

5. When the desired BEEP setting is displayed, press the











key to set the status and return to the measurement screen.

8.8 Zero (Auto/Manual)

There are two transducer zeroing options available in the TI-25DXL; auto and manual. The AUTO zero can be performed automatically without using a reference standard to zero the gauge (off block), while the MANUAL option requires a reference standard like the battery disk at the top of the gauge (on block). Additionally, the gauge can be set to use another reference standard if needed. Refer to section 5.1 for a complete explanation of the probe zero options.

The procedure to select the zero option only, is outlined below:

1. Press the  key to access the menu items/features.
2. Use the  and  keys to scroll through the items/features until the ZERO feature is being displayed.
3. Press the  key to edit the zero setting. The edit icon will be illuminated and flashing.
4. Use the  and  keys to select the auto/man option.

Note: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.




5. When the desired ZERO setting is displayed, press the  key to set the status and return to the measurement screen.


8.9 Velocity (VX)

When the velocity setting (VEL) is enabled, the TI-25MXT will display will the material velocity as the primary measurement quantity instead of dimensional thickness. The feature is generally used for basic “nodularity” testing, as velocity is a key part of density for determining hardness. An example might be casting manufacturers where the density/hardness will determine the strength of the material.



When this feature is enabled, the TI-25MXT is operating in reverse to the standard option of the gauge. Only the ‘one point’ calibration can be used with this feature active, and a manual or auto zero is still required. The TI-25MXT can be calibrated by entering the known velocity or entering the know thickness of the material at a given position on the test material. Refer to section 5.0 for a complete explanation of the zero and one point calibration procedure.

The procedure to enable the velocity feature is outlined below:

1. Press the  key to access the menu items/features.
2. Use the  and  keys to scroll through the items/features until the VX feature is being displayed.

3. Press the  key to edit the setting. The edit icon will be illuminated and flashing.

4. Use the  and  keys to select the on/off option.


Note: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes.



5. When the desired VX setting is displayed, press the  key to set the status and return to the measurement screen.


8.10 Probe Diameter

The PROB feature was added to improve linearity when using a specific probe diameter. The default standard setting is (.250") 0.250" 5MHZ HI Damped and works reasonably well using a general correction curve for all of our dual element transducers in our range. However, selecting the exact diameter of the transducer being used will offer additional linearity (accuracy). The five options found in our range of transducers are (.185, .187, .255, .257, .503, .505) followed by frequency inches. All of our transducer diameters and frequencies are marked on top of the transducer housing.



The procedure to select the probe/transducer diameter is outlined below:

1. Press the  key to access the menu items/features.

2) Use the  and  keys to scroll through the items/features until the PROB feature is being displayed.

3. Press the  key to edit the diameter setting. The edit icon will be illuminated and flashing.

4. Use the  and  keys to select the diameter option.

Note: Pressing the  key prior to pressing the  key will abort to the measurement screen without saving changes



5. When the desired PROB setting is displayed, press the  key to set the diameter and return to the measurement screen.

8.11 Lock

The lock feature was built into the TI-25MXT for the purpose of locking the operators out of editing any of the gauge settings, for purposes of consistency between operators. When the lock feature is enabled, the gauge calibration functionality cannot be altered, as well as any of the individual features in the gauge. The only keys that are always

unlocked are the power and probe zero keys, as these must remain unlocked for measurement functionality.



The procedure to enable/disable the lock feature is outlined below:

1. With the TI-25MXT powered off, press and hold down the  key while powering the TI-25MXT on. The lock icon will be illuminated on the display.
2. To unlock the TI-25MXT repeat step one, but hold down the  key while powering the TI-25MXT on.

8.12 Factory Defaults

The TI-25MXT can be reset to factory defaults at any time to restore the original gauge settings. This should only be used if the gauge is not functioning properly, or perhaps multiple features have been enabled and a clean start is needed.

The procedure to reset the gauge is outlined below:

1. With the TI-25MXT powered off, press and hold down the  and  keys while powering the TI-25MXT on.

NOTE: Once the measurement screen is displayed the keys can be released.

9.0 CONNECTIVITY AND POWER

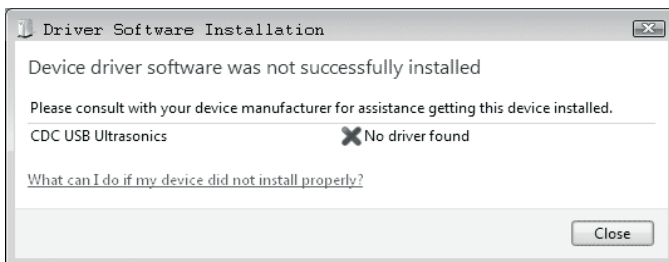
9.1 Connectivity

The TI-25MXT is equipped with a USB-C connector and offers serial over USB using a CDC (Communications Data Class) and software wedge to transfer data into common text editors and spreadsheet software programs as needed. The TI-25MXT does not have any internal memory to store data, but is used to connect to external storage devices such as SPC data collectors and PC based software programs.

We also offer a standard serial hardware option, as well as a wireless Bluetooth module that can be installed on the PC board of the TI-25MXT. Refer to our price list for additional information on communication module options and cables.

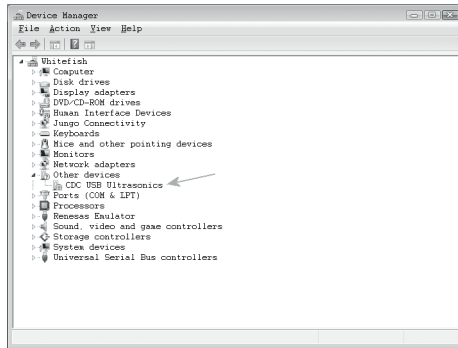
9.2 Installing Serial Driver (CDC)

When the TI-25MXT is powered on and connected to the PC, and no CDC driver was previously installed, the following message will be displayed:

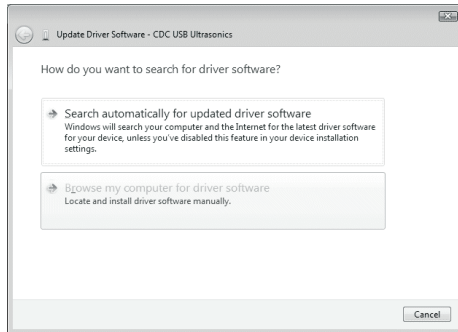


The driver file that needs to be installed can be downloaded directly from our website at www.dakotaultrasonics.comDUsoftware/CDC/CDC_Ultrasonics.inf, or can be found in the examples folder created on your PC by installing our DakView PC software, and located in the USB directory. The file name is CDC_Ultrasonics.inf, and can be downloaded and saved anywhere on your local PC.

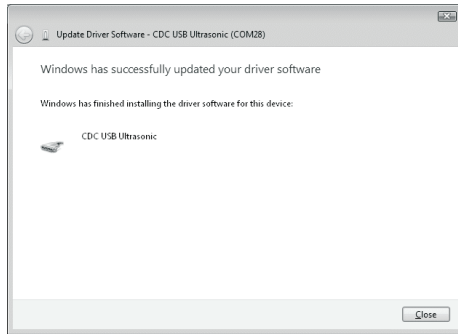
To install the driver, open Control Panel, followed by selecting Device Manager:



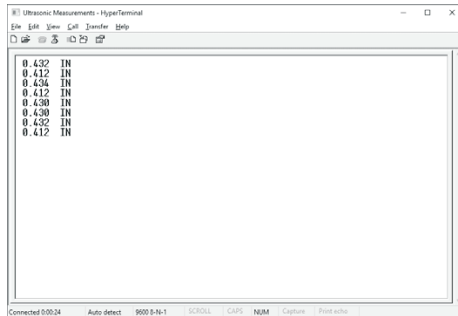
Right click on the CDC device as illustrated above, and select "update driver". The following window will appear:



Select “browse my computer” and navigate to the directory where the driver was saved on your PC and install the driver. When the installation is completed, the following window will be displayed:



Open device manager again to reference the communications port assigned to the CDC device, it will be displayed to the right of the CDC device. Now that the driver has been successfully installed, a ‘keyboard wedge’ with serial communications capability can be used to connect to the TI-25MXT and will capture the measurements to your PC when the ENTER key is pressed:



9.3 Line Power

The TI-25MXT can be powered using the standard USB-C to USB-A data cable (N-003-0330), by connecting directly to a USB port on your computer, or using a standard cell phone power adapter directly to an outlet. This is a convenient way to power the gauge for specific bench top applications in a factory line environment.

10.0 APPENDIX A – SOUND VELOCITY TABLE

Material	Sound Velocity in/us		Sound Velocity m/s
Aluminum	0.2510		6375
Beryllium	0.5080		12903
Brass	0.1730		4394
Bronze	0.1390		3531
Cadmium	0.1090		2769
Columbium	0.1940		4928
Copper	0.1830		4648
Glass (plate)	0.2270		5766
Glycerine	0.0760		1930
Gold	0.1280		3251
Inconel	0.2290		5817
Iron	0.2320		5893
Cast Iron	0.1800	(approx)	4572
Lead	0.0850		2159
Magnesium	0.2300		5842
Mercury	0.0570		1448
Molybdenum	0.2460		6248
Monel	0.2110		5359
Nickel	0.2220		5639
Nylon	0.1060	(approx)	2692
Platinum	0.1560		3962
Plexiglas	0.1060		2692
Polystyrene	0.0920		2337
PVC	0.0940		2388
Quartz glass	0.2260		5740
Rubber vulcanized	0.0910		2311
Silver	0.1420		3607
Steel (1020)	0.2320		5893
Steel (4340)	0.2330		5918
Teflon	0.0540		1372
Tim	0.1310		3327
Titanium	0.2400		6096
Tungsten	0.2040		5182
Uranium	0.1130		3378
Water	0.0580		1473
Zinc	0.1660		4216
Zirconium	0.1830		4648

11.0 APPENDIX B – APPLICATION NOTES

Measuring pipe and tubing

When measuring a piece of pipe to determine the thickness of the pipe wall, orientation of the transducers is important. The transducer should be oriented so that the gap (sound barrier) in the wear face is perpendicular (at a right angle) to the length (long axis) of the tubing, allowing both sides of the transducer to make the same amount of contact. The transducer orientation can either be parallel or perpendicular for large diameter piping, as it's much easier to ensure both sides are making similar contact.



Measuring hot surfaces

The velocity of sound through a substance is dependent on its temperature. As materials heat up, the velocity of sound through them decreases. In most applications with surface temperatures less than about 200°F (100°C), no special procedures must be observed. At temperatures above this point, the change in sound velocity of the material being measured starts to have a noticeable effect upon ultrasonic measurement.

At such elevated temperatures, it is recommended that the user perform calibration on a sample piece of known thickness, which is at or near the temperature of the material to be measured. This will allow the TI-25MXT to correctly calculate the velocity of sound through the hot material.

Expansion and contraction of the transducer based on temperature, and a varying temperature gradient, will also affect the measurement in a pulse-echo (P-E) measurement mode. It is recommended that a “transducer zero” be performed often to account for the delay line changing length and adversely affecting the accuracy of the measurements.

When performing measurements on hot surfaces, it may also be necessary to use a specially constructed high-temperature transducer. These transducers are built using materials which can withstand high temperatures. Even so, it is recommended that the probe be left in contact with the surface for as short a time as needed (intermittent contact) to acquire a stable measurement.

Measuring laminated materials

Laminated materials are unique in that their density (and therefore sound-velocity) may vary considerably from one piece to another. Some laminated materials may even exhibit noticeable changes in sound-velocity across a single surface. The only way to reliably measure such materials is by performing a calibration procedure on a sample piece of known thickness. Ideally, this sample material should be a part of the same piece being measured, or at least from the same lamination batch. By calibrating to each test piece individually, the effects of variation of sound-velocity will be minimized. If the variation is relatively close, averaging the sound velocities to minimize error is another option.

An additional important consideration when measuring laminates is that many included air gaps or pockets which will cause an early reflection of the ultrasound beam. This effect will be noticed as a sudden decrease in thickness in an otherwise regular surface. While this may impede accurate measurement of total material thickness, it does provide the user with positive indication of air gaps in the laminate.

Measuring through paint & coatings

Measuring through paints and coatings are also unique, in that the velocity of the paint/coating will be significantly different from the actual material being measured. A perfect example of this would be a mild steel pipe with .025" of coating on the surface. Where the velocity of the steel pipe is .2330 in/ μ sec, and the velocity of the paint is .0850 in/ μ sec. If the user is calibrated for mild steel pipe and measures through both materials, the actual coating thickness will appear to be approximately 3 times thicker than it actually is, as a result of the differences in velocity.

12.0 WARRANTY

ELECTROMATIC Equipment Co., Inc. (ELECTROMATIC) warrants to the original purchaser that this product is of merchantable quality and confirms in kind and quality with the descriptions and specifications thereof. Product failure or malfunction arising out of any defect in workmanship or material in the product existing at the time of delivery thereof which manifests itself within one year from the sale of such product, shall be remedied by repair or replacement of such product, at ELECTROMATIC's option, except where unauthorized repair, disassembly, tampering, abuse or misapplication has taken place, as determined by ELECTROMATIC. All returns for warranty or non-warranty repairs and/or replacement must be authorized by ELECTROMATIC, in advance, with all repacking and shipping expenses to the address below to be borne by the purchaser.

THE FOREGOING WARRANTY IS IN LIEU OF ALL OTHER WARRANTIES, EXPRESSED OR IMPLIED, INCLUDING BUT NOT LIMITED TO, THE WARRANTY OF MERCHANTABILITY AND FITNESS FOR ANY PARTICULAR PURPOSE OR APPLICATION. ELECTROMATIC SHALL NOT BE RESPONSIBLE NOR LIABLE FOR ANY CONSEQUENTIAL DAMAGE, OF ANY KIND OR NATURE, RESULTING FROM THE USE OF SUPPLIED EQUIPMENT, WHETHER SUCH DAMAGE OCCURS OR IS DISCOVERED BEFORE, UPON OR AFTER REPLACEMENT OR REPAIR, AND WHETHER OR NOT SUCH DAMAGE IS CAUSED BY MANUFACTURER'S OR SUPPLIER'S NEGLIGENCE WITHIN ONE YEAR FROM INVOICE DATE.

Some State jurisdictions or States do not allow the exclusion or limitation of incidental or consequential damages, so the above limitation may not apply to you. The duration of any implied warranty, including, without limitation, fitness for any particular purpose and merchantability with respect to this product, is limited to the duration of the foregoing warranty. Some states do not allow limitations on how long an implied warranty lasts but, notwithstanding, this warranty, in the absence of such limitations, shall extend for one year from the date of invoice.

ELECTROMATIC Equipment Co., Inc.
600 Oakland Ave. Cedarhurst, NY 11516—USA
Tel: 1-800-645-4330/ Tel: 516-295-4300/ Fax: 516-295-4399

Every precaution has been taken in the preparation of this manual. Electromatic Equipment Co., Inc., assumes no responsibility for errors or omissions. Neither is any liability assumed for damages resulting from the use of information contained herein. Any brand or product names mentioned herein are used for identification purposes only, and are trademarks or registered trademarks of their respective holders

NOTES

